

WHAT IS CLAIMED IS:

- Pub 2001/0048753  
Pub. 41, 45, 73  
5 10 15 20 25
1. A method of describing object region data about an object in video data over a plurality of frames, said method comprising:  
a.) approximating the object using a figure for each of said frames;  
b.) extracting a plurality of points representing the figure for each of said frames;  
c.) approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, position data about one of said plurality of points and relative position data about remaining points with reference to said one of said plurality of points; and  
d.) describing the object region data using the functions.
2. The method according to claim 1, wherein said object region data comprises information representing a range of frames in which the object exists in the video data and information identifying the figure approximating the object region.
3. The method according to claim 1, wherein said object region data comprises one of information representing related information linking to the object and information representing a method of accessing the related information.
4. The method according to claim 1, wherein said

relative position data are components of differential vectors between the one of said plurality of points and remaining points.

5. The method according to claim 1, wherein said object region data comprises parameters of the functions.

6. A method of describing object region data about an object in video data over a plurality of frames, said method comprising:

- 10 a) approximating the object using a figure for each of said frames;
- b) extracting a plurality of points representing the figure for each of said frames;
- c) approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, position data about said plurality of points in a reference frame and relative position data about said plurality of points in a succeeding frame with reference to the position data about said plurality of points in the reference frame; and
- 20 d) describing the object region data using the functions.

7. The method according to claim 6, wherein said object region data comprises information representing a range of frames in which the object exists in the video data and information identifying the figure approximating the object region.

8. The method according to claim 6, wherein said object region data comprises one of information representing related information linking to the object and information representing a method of accessing the related information.

5

9. The method according to claim 6, wherein said relative position data are components of differential vectors between said plurality of points in the reference frame and said plurality of points in the succeeding frame.

10

10. The method according to claim 6, wherein said object region data comprises parameters of the functions.

15

11. A method of describing object region data about an object in video data over a plurality of frames, said method comprising:

20

- a.) approximating the object using a figure for each of said frames;
- b.) extracting a plurality of points representing the figure for each of said frames;
- c.) approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and
- d.) describing the object region data using the functions and depth information of the object.

25

12. The method according to claim 11, wherein said

TOP SECRET//COMINT  
SUBJ

object region data comprises information representing a range of frames in which the object exists in the video data and information identifying the figure approximating the object region.

5        13. The method according to claim 11, wherein said object region data comprises one of information representing related information linking to the object and information representing a method of accessing the related information.

10        14. The method according to claim 11, wherein said object region data is described by using the depth information of the object and parameters of the functions.

15        15. The method according to claim 11, wherein said depth information is a relative depth and has a discrete level value.

20        16. A method of describing object region data about an object in video data over a plurality of frames, said method comprising:

              approximating the object using a figure for each of said frames;

              extracting a plurality of points representing the figure for each of said frames;

25        approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and

describing the object region data using the functions and display flag information indicating a range of frames in which the object or each of said points is visible or not.

5        17. The method according to claim 16, wherein said object region data comprises information representing a range of frames in which the object exists in the video data and information identifying the figure approximating the object region.

10      18. The method according to claim 16, wherein said object region data comprises one of information representing related information linking to the object and information representing a method of accessing the related information.

15      19. The method according to claim 16, wherein said object region data is described by using the display flag information and parameters of the functions.

20      20. A method of describing object region data about an object in video data over a plurality of frames, said method comprising:

- a) approximating the object using a figure for each of said frames;
- b) extracting a plurality of points representing the figure for each of said frames;
- c) approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said

TOP SECRET//SUBJ  
REF ID: A610

plurality of points; and

- d.) describing the object region data using the functions and object passing range information indicating a range where the figure approximating the object exist over said plurality of frames.

21. The method according to claim 20, wherein said object region data comprises information representing a range of frames in which the object exists in the video data and information identifying the figure approximating the object region.

10 22. The method according to claim 20, wherein said object region data comprises one of information representing related information linking to the object and information representing a method of accessing the related information.

15 23. The method according to claim 20, wherein said object region data is described by using the object passing range information and parameters of the functions.

20 24. A method of describing object region data about an object moving in a panorama image formed by combining a plurality of frames with being overlapped, said method comprising:

- a.) approximating the object in the panorama image using a figure;
- b.) extracting a plurality of points representing the figure in a coordinate system of the panorama image;

SEARCHED  
INDEXED  
SERIALIZED  
FILED  
JULY 20 1998  
FBI - PORTLAND

- c.) approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and
- 5 d.) describing the object region data using the functions.

25. The method according to claim 24, wherein said object region data comprises information representing a range of frames in which the object exists in the video data and information identifying the figure approximating the object region.

10  
15 26. The method according to claim 24, wherein said object region data comprises one of information representing related information linking to the object and information representing a method of accessing the related information.

27. The method according to claim 24, wherein said object region data comprises parameters of the functions.

20 28. An article of manufacture comprising a computer usable medium having computer readable program code means embodied therein and for An article of manufacture comprising a computer usable medium having computer readable program code means embodied therein and, for describing object region data about an object in video data over a plurality of frames, the computer readable program code means comprising:

25

agent

- a.) computer readable program code means for approximating the object using a figure for each of said frames;
- 5 b.) computer readable program code means for extracting a plurality of points representing the figure for each of said frames;
- c.) computer readable program code means for approximating trajectories with functions, the trajectories being obtained by arranging, in the frames 10 advancing direction, position data about one of said plurality of points and relative position data about remaining points with reference to said one of said plurality of points; and
- d.) computer readable program code means for 15 describing the object region data using the functions.

29. An article of manufacture comprising a computer usable medium having computer readable program code means embodied therein and for describing object region data about an object in video data over a plurality of frames, the computer readable program code 20 means comprising:

computer readable program code means for approximating the object using a figure for each of said frames;

25 computer readable program code means for extracting a plurality of points representing the figure for each of said frames;

TOP SECRET SUB B NO

computer readable program code means for  
approximating trajectories with functions, the  
trajectories being obtained by arranging, in the frames  
advancing direction, position data about said plurality  
5 of points in a reference frame and relative position  
data about said plurality of points in a succeeding  
frame with reference to the position data about said  
plurality of points in the reference frame; and

10 computer readable program code means for  
describing the object region data using the functions.

30. An article of manufacture comprising  
a computer usable medium having computer readable  
program code means embodied therein and for describing  
object region data about an object in video data over  
15 a plurality of frames, the computer readable program  
code means comprising:

computer readable program code means for  
approximating the object using a figure for each of  
said frames;

20 computer readable program code means for  
extracting a plurality of points representing the  
figure for each of said frames;

computer readable program code means for  
approximating trajectories with functions, the  
trajectories being obtained by arranging, in the frames  
advancing direction, data indicating positions of said  
25 plurality of points; and

TELETYPE  
SUBB

computer readable program code means for  
describing the object region data using the functions  
and depth information of the object.

31. An article of manufacture comprising  
5 a computer usable medium having computer readable  
program code means embodied therein and for describing  
object region data about an object in video data over  
a plurality of frames, the computer readable program  
code means comprising:
- 10 a) computer readable program code means for  
approximating the object using a figure for each of  
said frames;
- 15 computer readable program code means for  
extracting a plurality of points representing the  
figure for each of said frames;
- 20 c) computer readable program code means for  
approximating trajectories with functions, the  
trajectories being obtained by arranging, in the frames  
advancing direction, data indicating positions of said  
plurality of points; and
- 25 d) computer readable program code means for  
describing the object region data using the functions  
and display flag information indicating a range of  
frames in which the object or each of said points is  
visible or not.

32. An article of manufacture comprising  
a computer usable medium having computer readable

TELETYPE REC'D 10-16-10

*[Handwritten signature]*

program code means embodied therein and for describing object region data about an object in video data over a plurality of frames, the computer readable program code means comprising:

5           computer readable program code means for approximating the object using a figure for each of said frames;

10          computer readable program code means for extracting a plurality of points representing the figure for each of said frames;

15          computer readable program code means for approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and

20          computer readable program code means for describing the object region data using the functions and object passing range information indicating a range where the figure approximating the object exist over said plurality of frames.

33. An article of manufacture comprising  
a computer usable medium having computer readable  
program code means embodied therein and for describing  
object region data about an object moving in a panorama  
image formed by combining a plurality of frames with  
being overlapped, the computer readable program code  
means comprising:

SEARCHED  
INDEXED  
SERIALIZED  
FILED  
JULY 19 1988  
FBI - BOSTON

computer readable program code means for approximating the object in the panorama image using a figure;

5 computer readable program code means for extracting a plurality of points representing the figure in a coordinate system of the panorama image;

10 computer readable program code means for approximating trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and

computer readable program code means for describing the object region data using the functions.

34. A computer data signal embodied in a carrier wave, the computer data signal capable of describing object region data about an object in video data over a plurality of frames, the computer data signal comprising:

20 program code portion for causing a computer to approximate the object using a figure for each of said frames;

program code portion for causing a computer to extract a plurality of points representing the figure for each of said frames;

25 program code portion for causing a computer to approximate trajectories with functions, the trajectories being obtained by arranging, in the frames

SEARCHED INDEXED  
SERIALIZED FILED  
JULY 19 1988

JULY 19 1988

advancing direction, position data about one of said plurality of points and relative position data about remaining points with reference to said one of said plurality of points; and

5 program code portion for causing a computer to describe the object region data using the functions.

35. A computer data signal embodied in a carrier wave, the computer data signal capable of describing object region data about an object in video data over  
10 a plurality of frames, the computer data signal comprising:

program code portion for causing a computer to approximate the object using a figure for each of said frames;

15 program code portion for causing a computer to extract a plurality of points representing the figure for each of said frames;

program code portion for causing a computer to approximate trajectories with functions, the  
20 trajectories being obtained by arranging, in the frames advancing direction, position data about said plurality of points in a reference frame and relative position data about said plurality of points in a succeeding frame with reference to the position data about said plurality of points in the reference frame; and

program code portion for causing a computer to describe the object region data using the functions.

SEARCHED INDEXED  
SERIALIZED FILED  
JULY 1970

36. A computer data signal embodied in a carrier wave, the computer data signal capable of describing object region data about an object in video data over a plurality of frames, the computer data signal comprising:

5 program code portion for causing a computer to approximate the object using a figure for each of said frames;

10 program code portion for causing a computer to extract a plurality of points representing the figure for each of said frames;

15 program code portion for causing a computer to approximate trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and

program code portion for causing a computer to describe the object region data using the functions and depth information of the object.

20 37. A computer data signal embodied in a carrier wave, the computer data signal capable of describing object region data about an object in video data over a plurality of frames, the computer data signal comprising:

25 program code portion for causing a computer to approximate the object using a figure for each of said frames;

SEARCHED  
INDEXED  
SERIALIZED  
FILED  
JULY 13 1980

*JBH*

program code portion for causing a computer to extract a plurality of points representing the figure for each of said frames;

5 program code portion for causing a computer to approximate trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and

10 program code portion for causing a computer to describe the object region data using the functions and display flag information indicating a range of frames in which the object or each of said points is visible or not.

15 38. A computer data signal embodied in a carrier wave, the computer data signal capable of describing object region data about an object in video data over a plurality of frames, the computer data signal comprising:

20 program code portion for causing a computer to approximate the object using a figure for each of said frames;

program code portion for causing a computer to extract a plurality of points representing the figure for each of said frames;

25 program code portion for causing a computer to approximate trajectories with functions, the trajectories being obtained by arranging, in the frames

SEARCHED  
INDEXED  
SERIALIZED  
FILED  
JULY 19 1968  
FBI - BOSTON

advancing direction, data indicating positions of said plurality of points; and

program code portion for causing a computer to describe the object region data using the functions and  
5 object passing range information indicating a range where the figure approximating the object exist over said plurality of frames.

39. A computer data signal embodied in a carrier wave, the computer data signal capable of describing object region data about an object moving in a panorama image formed by combining a plurality of frames with being overlapped, the computer data signal comprising:

10 program code portion for causing a computer to approximate the object in the panorama image using  
15 a figure;

program code portion for causing a computer to extract a plurality of points representing the figure in a coordinate system of the panorama image;

program code portion for causing a computer to  
20 approximate trajectories with functions, the trajectories being obtained by arranging, in the frames advancing direction, data indicating positions of said plurality of points; and

25 program code portion for causing a computer to describe the object region data using the functions.

SEARCHED INDEXED SERIALIZED FILED  
JULY 21 1972